



第 2 次作业

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Homework 2

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1 Question

1. 路金甫书 (第三版) 第二章习题 1,2,3 (这里稳定性用傅里叶方法讨论)

(陆金甫 & 关治, 2016, pp. 43-44)

1. 讨论对流方程

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0, \quad a > 0$$

的差分格式

$$\frac{u_j^{n+1} - u_j^n}{\tau} + a \frac{u_j^{n+1} - u_{j-1}^{n+1}}{h} = 0$$

的截断误差及稳定性.

2. 题 1 中差分格式改为

$$\frac{u_j^{n+1} - u_j^n}{\tau} + a \frac{u_{j+1}^{n+1} - u_j^{n+1}}{h} = 0$$

讨论其截断误差及稳定性。

3. 讨论扩散方程

$$\frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2}, \quad a > 0$$

的差分格式

$$\frac{3}{2} \frac{u_j^{n+1} - u_j^n}{\tau} - \frac{1}{2} \frac{u_j^n - u_j^{n-1}}{\tau} = a \frac{u_{j+1}^{n+1} - 2u_j^{n+1} + u_{j-1}^{n+1}}{h^2}$$

的精度及稳定性.

2. 讨论显式龙格-库塔2(RK2)稳定域包含虚轴哪些部分。针对对流方程 $u_t + u_x = 0$, 空间用中心差分, 时间用显式龙格-库塔2, 固定网格比 τ/h 的方式让步长趋于0. 讨论该方法稳定性。



2 Solutions

MATH6008 第二次作业 2022.3.14 (due date)

1. 解, 截断误差

$$T_j^{n+1} = \frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{\tau} + \frac{a}{h} (u(x_j, t_{n+1}) - u(x_{j-1}, t_{n+1}))$$

在 (x_j, t_{n+1}) 处 Taylor 展开

$$\begin{aligned} &= \frac{1}{\tau} \left(-u_t(x_j, t_{n+1}) \cdot (-\tau) + \mathcal{O}(\tau^2) \right) \\ &\quad + \frac{a}{h} \left(-u_x(x_j, t_{n+1}) \cdot (-h) + \mathcal{O}(h^2) \right) \\ &= (u_t' + au_x) \Big|_{(x_j, t_{n+1})} + \mathcal{O}(\tau + h) \\ &= \mathcal{O}(\tau + h). \end{aligned}$$

用 Fourier 方法讨论稳定性. 格式写成

$$u_j^{n+1} = u_j^n - \alpha \lambda (u_j^{n+1} - u_{j-1}^{n+1}), \quad \lambda = \tau/h.$$

作 semi-DFT, $(u_j^n \rightarrow V_n e^{i2\pi jh})$, \Rightarrow

$$\begin{aligned} V_{n+1} &= V_n - \alpha \lambda V_{n+1} (1 - e^{i2\pi h}) \\ &= V_n / (1 + \alpha \lambda (1 - e^{i2\pi h})) \end{aligned}$$

$$\Rightarrow G(\xi; h, \tau) = 1 / (1 + \alpha \lambda (1 - e^{i2\pi h}))$$

$$\Rightarrow |G| = 1 / |1 + \alpha \lambda (1 - \cos(2\pi h)) - i \alpha \lambda \sin(2\pi h)| \leq 1 \quad (\forall 2\pi h \in [-\pi, \pi])$$

\therefore 不取入取何值, 格式均稳定.

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2. 解: 截断误差

$$\begin{aligned}
\tau_j^{n+1} &= \frac{1}{\tau} (u(x_j, t_{n+1}) - u(x_j, t_n)) + \frac{a}{h} (u(x_{j+1}, t_{n+1}) - u(x_j, t_{n+1})) \\
&= \frac{1}{\tau} (-u_t(x_j, t_{n+1})(-\tau) + O(\tau^2)) + \frac{a}{h} (-u_x(x_j, t_{n+1})(-h) + O(h^2)) \\
&= (u_t + au_x) \Big|_{(x_j, t_{n+1})} + O(\tau+h) \\
&= O(\tau+h).
\end{aligned}$$

格式写成 $u_j^{n+1} = u_j^n - a\lambda(u_{j+1}^{n+1} - u_j^{n+1})$. 为 semi-DFT

($u_j^n \rightarrow V_n e^{izh}$) $\Rightarrow V_{n+1} = V_n - a\lambda V_{n+1} (e^{izh} - 1) = V_n / (1 + a\lambda(e^{izh} - 1))$

\Rightarrow 增长因子 $G(z; h, \tau) = 1 / [1 + a\lambda(\cos(zh) - 1) + i a\lambda \sin(zh)]$

$\Rightarrow |G| = [1 + 2a^2\lambda^2 + 2a\lambda((1-a\lambda)\cos(\varphi h) - 1)]^{-1/2}$

介于(取遍, z 取遍 $[-\pi, \pi]$) 1, $|1 - 2a\frac{\tau}{h}| \geq 1$.

要 要使 $\forall \tau \leq \tau_0$: ~~$|G| \leq 1 + M\tau$~~ , 至少要有 ~~$|G| \leq 1$~~ ($\tau \rightarrow 0$)

1°. $|1 - 2a\frac{\tau}{h}| \leq 1 \Leftrightarrow a\frac{\tau}{h} \in [0, 1]$: 稳定.

2°. 不能放松上述限制使 $|G| \leq 1 + M\tau$ ($\forall \tau \leq \tau_0$). $\Delta?$

因 $|1 - 2a\frac{\tau}{h}| \leq 1 + M\tau$ ($\forall \tau \leq \tau_0$) \Rightarrow ~~$2a\frac{\tau}{h} \rightarrow$~~



3. 解: 截断误差

$$\begin{aligned}
 \tau_j^{n+1} &= \frac{3}{2} \frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{\tau} - \frac{1}{2} \frac{u(x_j, t_n) - u(x_{j-1}, t_n)}{\tau} - \frac{a}{h^2} (\\
 &\quad - \frac{a}{h^2} (u(x_{j+1}, t_{n+1}) - 2u(x_j, t_n) + u(x_{j-1}, t_{n+1})) \\
 &= \frac{1}{2} \frac{1}{\tau} (\frac{3}{2} u(x_j, t_{n+1}) - 2u(x_j, t_n) + \frac{1}{2} u(x_j, t_{n-1})) \\
 &\quad - \frac{a}{h^2} (u(x_{j+1}, t_{n+1}) - 2u(x_j, t_n) + u(x_{j-1}, t_{n+1})) \\
 &= \frac{1}{\tau} (-2u_t(x_j, t_n) \cdot (-\tau) + \frac{1}{2} \cdot u_t(x_j, t_n) \cdot (-2\tau) \\
 &\quad - 2u_{tt}(x_j, t_n) \cdot (\frac{\tau^2}{2}) + \frac{1}{2} u_{tt}(x_j, t_n) \cdot \frac{(\tau\tau)^2}{2} \\
 &\quad - 2u_{xx}(x_j, t_n) \cdot \frac{\tau^3}{6} + \frac{1}{2} \cdot u_{xx}(x_j, t_n) \cdot \frac{(\tau\tau)^3}{3} + o(\tau^3)) \\
 &\quad - \frac{a}{h^2} (u_{xxx}(x_j, t_{n+1}) \cdot \frac{h^2}{2} \cdot 2 + \frac{1}{4!} u_{xxx}(x_j, t_{n+1}) h^4 \cdot 2 + o(h^4)) \\
 &= (u_t - au_{xx}) \Big|_{(x_j, t_{n+1})} + O(\tau^2 + h^2)
 \end{aligned}$$

\therefore 时间精度和空间精度都为 2 阶 \Rightarrow 具有二阶精度.

引入 $v_j^n = u_j^{n-1}$, $\mu = \tau/h^2$, 格式重写为

$$\begin{cases}
 (\frac{3}{2} + 2a\mu) u_j^{n+1} = 2u_j^n - \frac{1}{2} v_j^n + a\mu (u_{j+1}^{n+1} + u_{j-1}^{n+1}), \\
 v_j^{n+1} = u_j^n.
 \end{cases}$$

引入 $U_j^n = [u_j^n, v_j^n]^T$, \Rightarrow

$$\begin{bmatrix} \frac{3}{2} + 2a\mu & 0 \\ 1 & 1 \end{bmatrix} U_j^{n+1} = \begin{bmatrix} 2 & -1/2 \\ 1 & 1 \end{bmatrix} U_j^n + \begin{bmatrix} a\mu & 0 \\ 0 & 0 \end{bmatrix} (U_{j+1}^{n+1} + U_{j-1}^{n+1}).$$



作 semi-DFT ($U_j^n \rightarrow V_j^n e^{i2jh}$) \Rightarrow

$$\begin{bmatrix} \frac{3}{2} + 2\alpha\mu & 0 \\ 1 & 1 \end{bmatrix} V_{n+1} = \begin{bmatrix} 2 & -\frac{1}{2} \\ 1 & 0 \end{bmatrix} V_n + \begin{bmatrix} \alpha\mu \\ 0 \end{bmatrix} V_{n+1} \cdot (e^{i2jh} - e^{-i2jh})$$

$$\Rightarrow V_{n+1} = \begin{bmatrix} \frac{3}{2} + 4\alpha\mu \sin^2 \frac{2jh}{\nu} & 0 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 2 & -\frac{1}{2} \\ 1 & 0 \end{bmatrix} V_n$$

$$\Rightarrow \text{增长矩阵 } G(\alpha; h, \nu) = \begin{bmatrix} \frac{4}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} & \frac{-1}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} \\ 1 & 0 \end{bmatrix}$$

特征值 p 满足特征方程

$$0 = |pI - G| = \begin{vmatrix} p - \frac{4}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} & \frac{1}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} \\ -1 & p \end{vmatrix}$$

$$= p^2 - \frac{4p}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} + \frac{1}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}}$$

$$\Rightarrow p = \frac{\sqrt{2 \pm \sqrt{1 - 8\alpha\mu \sin^2 \frac{2jh}{\nu}}}}{3 + 8\alpha\mu \sin^2 \frac{2jh}{\nu}} \Rightarrow \text{稳定性?}$$

4. 解: RK2 (显式) 格式:

$$\begin{cases} U_{n+1/2}^* = \frac{\tau}{2} f(t_n, U_n) + U_n, \\ U_{n+1} = \tau f(t_{n+1/2}, U_{n+1/2}^*) + U_n. \end{cases}$$

将其用于线性问题 $u' = \lambda u$, $f(t, u) = \lambda u$, \Rightarrow

$$\begin{cases} U_{n+1/2}^* = \frac{\tau}{2} \cdot \lambda U_n + U_n, \\ U_{n+1} = \tau \cdot \lambda U_{n+1/2}^* + U_n \end{cases}$$

$$\Rightarrow U_{n+1} = \tau \lambda \left(\frac{\tau \lambda}{2} U_n + U_n \right) + U_n = U_n \left[1 + \tau \lambda \left(1 + \frac{\tau \lambda}{2} \right) \right]$$

$$\Rightarrow \text{稳定域 } \mathcal{D} := \left\{ z \in \mathbb{C} \mid \left| 1 + z \left(1 + \frac{z}{2} \right) \right| \leq 1 \right\}$$

$$= \left\{ z = x + iy \mid (x^2 - 4^2 + 2x + 2)^2 + 4y^2(1+x)^2 - 4 \leq 0 \right\}.$$



$$\Rightarrow D \cap \{z = x + iy \mid x=0, y \in \mathbb{R}\} \text{ (虚轴)} = \{z = iy \mid y^4 \leq 0\} = \{(0,0)\},$$

i.e. 虚轴上仅原点在稳定域中.

$$u_t + u_{xx} = 0 \xrightarrow{\text{时间中点差分}} u_j^{n+1} + \frac{u_{j+1}^n - u_{j-1}^n}{2h} = 0$$

显式 RK2

$$\begin{cases} u_j^{n+1/2} = u_j^n + \frac{\tau}{2} \left[-\frac{u_{j+1}^n - u_{j-1}^n}{2h} \right], \\ u_j^{n+1} = u_j^n + \tau \left[-\frac{u_j^{n+1/2} + u_j^{n+1/2}}{2h} \right] \end{cases}$$

$$\begin{aligned} \Rightarrow u_j^{n+1} &= u_j^n - \frac{\tau}{2h} \left\{ \left[u_{j+1}^n - \frac{\tau}{2} \frac{u_{j+2}^n - u_{j-1}^n}{2h} \right] - \left[u_{j-1}^n - \frac{\tau}{2} \frac{u_j^n - u_{j-2}^n}{2h} \right] \right\} \\ &= \frac{\tau^2}{8h^2} u_{j-2}^n + \frac{\tau}{2h} u_{j-1}^n - \frac{\tau^2}{4h^2} u_j^n - \frac{\tau}{2h} u_{j+1}^n + \frac{\tau^2}{8h^2} u_{j+2}^n. \end{aligned}$$

$$U_j^n = (u_j^n)_{j=0,1,\dots}, \text{ 格式写成 } U_j^{n+1} = A U_j^n, \text{ (周期边界)} \Rightarrow$$

$$A = \begin{bmatrix} -\frac{\tau}{4h^2} & -\frac{\tau}{2h} & \frac{\tau^2}{8h^2} & 0 & \dots & \dots & \frac{\tau^2}{8h^2} & \frac{\tau}{2h} \\ \frac{\tau}{2h} & -\frac{\tau^2}{4h^2} & -\frac{\tau}{2h} & \frac{\tau^2}{8h^2} & 0 & \dots & 0 & \frac{\tau^2}{8h^2} \\ \frac{\tau^2}{8h^2} & \frac{\tau^2}{2h} & -\frac{\tau^2}{4h^2} & -\frac{\tau}{2h} & \frac{\tau^2}{8h^2} & 0 & \dots & 0 \\ 0 & \frac{\tau^2}{8h^2} & \dots & & & & & \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{bmatrix}$$

... (循环)

$\Rightarrow A$ 的特征值 $\lambda_p = \dots$

\Rightarrow [稳定性], 必须 $\lambda_p \tau \in D, \forall p, \forall \tau \leq \tau_0$.

$\Rightarrow \tau$ 应选 \dots .



References

陆金甫, & 关治. (2016). *偏微分方程数值解法* (3 ed.). 清华大学出版社.